

Hopewell Senior High School

**Robotic Design and Coding Fundamentals: 1**

## Unit 6 Quiz

Due Date: **October 17, 2023**

Instructor: **Lori Colangelo**

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**ID: 1309**

Name: \_\_\_\_\_

Score:  / 100

Question 1

/1

This is called a common block.



- True
- False

Question 2

/1

Which of the following is the best description of what the Eye Sensor does?

- It reports the (X,Y) position of the VR Robot.
- It reports the distance between the VR Robot and the nearest solid object.
- It can be controlled to pick up and drop disks with metal cores.
- It detects if there is an object present and if so, the color of that object.

Question 3

/1

A VR Robot has one Eye Sensor.

- True
- False

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Question 4

/1

What does this Switch Block do?

```
front_eye.near_object()
```

- The Distance Sensor near object block reports if the Eye Sensor is close enough to an object to detect a color (red, green, blue, none).
- The Eye Sensor near object block reports if the Eye Sensor is close enough to an object to detect a color (red, green, blue, none).
- The Eye Sensor near object block reports if the Eye Sensor not working.
- The Eye Sensor near object block reports if the Eye Sensor is close enough to an object to detect a location.

Question 5

/1

The color the sensor is looking for in this example is

```
front_eye.detect (RED)
```

- Blue
- Green
- Red
- Black

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Question 6

 /1

In this code the VR Robot will turn right if it detects green and turn left if it detects blue.

```
when started
  If Front Eye detects green then turn right
  if front_eye.detect(GREEN):
    drivetrain.turn_for(RIGHT, 90, DEGREES)
  If Front Eye detects blue then turn left
  if front_eye.detect(BLUE):
    drivetrain.turn_for(LEFT, 90, DEGREES)
  If Front Eye detects red then stop
  if front_eye.detect(RED):
    drivetrain.stop()
```

- True  
 False

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Question 7

 /1

In the example what happens is the VR Robot detects red?

```
when started
  If Front Eye detects green then turn right
  if front_eye.detect(GREEN):
    drivetrain.turn_for(RIGHT, 90, DEGREES)
  If Front Eye detects blue then turn left
  if front_eye.detect(BLUE):
    drivetrain.turn_for(LEFT, 90, DEGREES)
  If Front Eye detects red then stop
  if front_eye.detect(RED):
    drivetrain.stop()
```

- Turns left
- Turns right
- Stops driving
- Drive forward.

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Question 8

/1

In this project, the robot is using conditionals.

```
when started
  If Front Eye detects green then turn right
  if front_eye.detect(GREEN):
    drivetrain.turn_for(RIGHT, 90, DEGREES)
  If Front Eye detects blue then turn left
  if front_eye.detect(BLUE):
    drivetrain.turn_for(LEFT, 90, DEGREES)
  If Front Eye detects red then stop
  if front_eye.detect(RED):
    drivetrain.stop()
  If Front Eye detects none then drive forward
  if front_eye.detect(NONE):
    drivetrain.drive(FORWARD())
```

- True
- False

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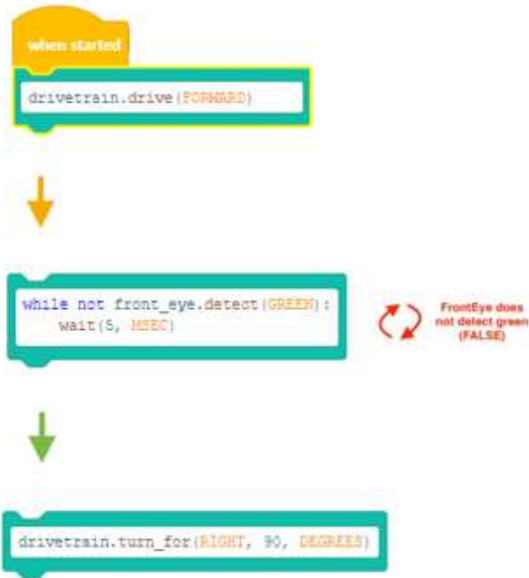
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Question 9

/1

The If then block is the same as the wait until block.



- True
- False

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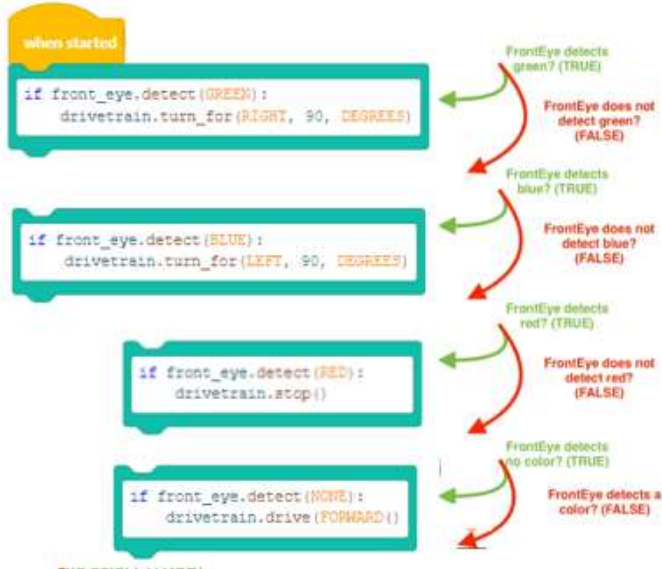
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Question 10

/1

If then blocks require the VR Robot to make a decision. If the condition is TRUE, then the blocks inside the If then C block are run. If the condition is FALSE, then the blocks inside the If then C block are skipped.



- True
- False

Question 11

/1

Will this project get the VR Robot through the Disk Maze Challenge successfully?





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Question 12

/4

Match Conditionals (Block and Switch Block).

1.



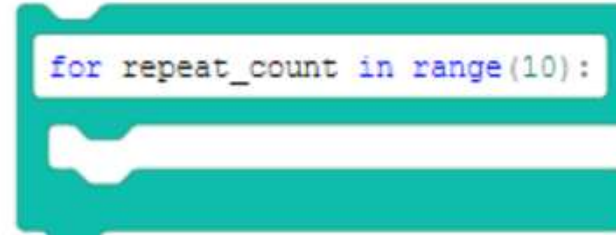
A.



2.



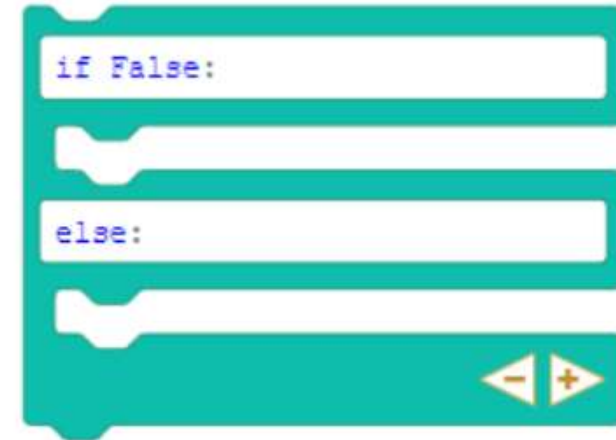
B.



3.



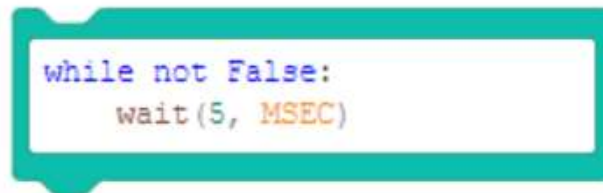
C.



4.



D.



Answer Key

Possible Points: 15 Factor: x1.00 Test Value: 15

**Instructions for grading:** Grade each question and tally the score to obtain the total test points. If the factor does not equal 1, multiply the total points by the factor to obtain the student's final score.

## Question 1

This is called a common block.



False

1 possible pts.

## Question 2

Which of the following is the best description of what the Eye Sensor does?

It detects if there is an object present and if so, the color of that object.

1 possible pts.

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Answer Key

Possible Points: 15 Factor: x1.00 Test Value: 15

## Question 3

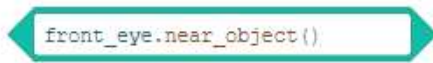
A VR Robot has one Eye Sensor.

 False

1 possible pts.

## Question 4

What does this Switch Block do?

A switch block with a light blue background and a dark blue border. The code 'front\_eye.near\_object()' is written in a monospace font inside the block. The block has a rounded left side and a pointed right side. The Eye Sensor near object block reports if the Eye Sensor is close enough to an object to detect a color (red, green, blue, none).

1 possible pts.

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Answer Key

Possible Points: 15 Factor: x1.00 Test Value: 15

Question 5

The color the sensor is looking for in this example is

```
front_eye.detect (RED)
```

Red

1 possible pts.

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Answer Key

Possible Points: 15 Factor: x1.00 Test Value: 15

## Question 6

In this code the VR Robot will turn right if it detects green and turn left if it detects blue.

```
when started
  If Front Eye detects green then turn right
  if front_eye.detect(GREEN):
    drivetrain.turn_for(RIGHT, 90, DEGREES)
  If Front Eye detects blue then turn left
  if front_eye.detect(BLUE):
    drivetrain.turn_for(LEFT, 90, DEGREES)
  If Front Eye detects red then stop
  if front_eye.detect(RED):
    drivetrain.stop()
```

 True

1 possible pts.

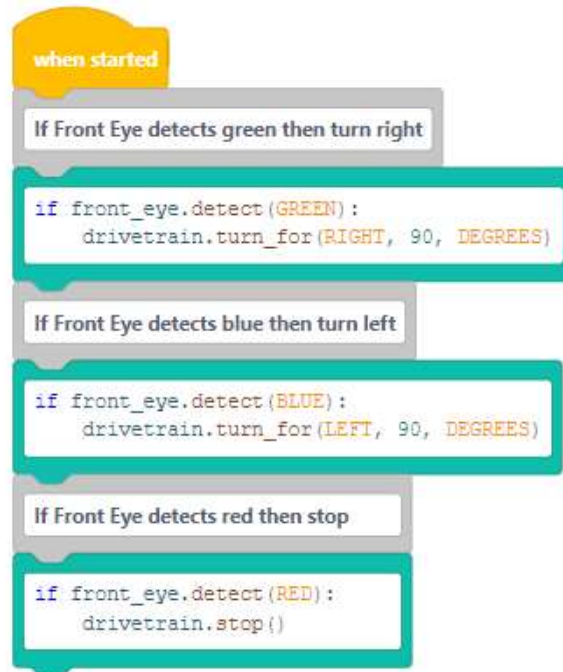
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Answer Key

Possible Points: 15 Factor: x1.00 Test Value: 15

Question 7



In the example what happens is the VR Robot detects red?

Stops driving

1 possible pts.

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Answer Key

Possible Points: 15 Factor: x1.00 Test Value: 15

## Question 8

In this project, the robot is using conditionals.

 True

1 possible pts.

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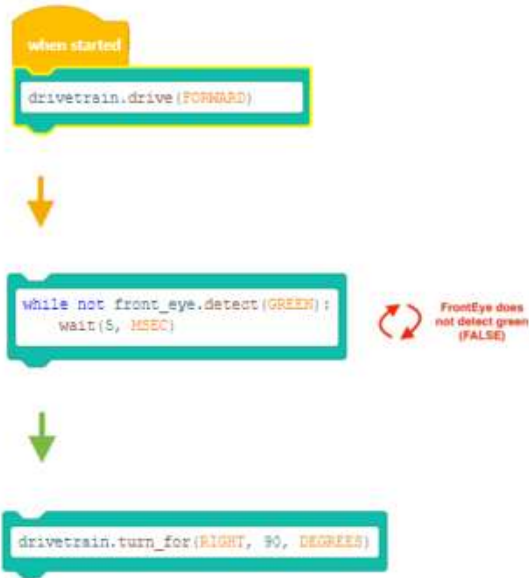


Answer Key

Possible Points: 15 Factor: x1.00 Test Value: 15

Question 9

The If then block is the same as the wait until block.



False

1 possible pts.

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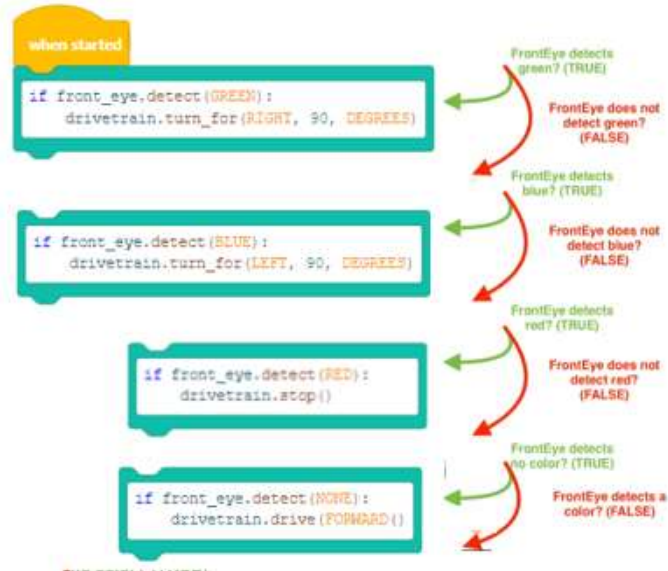
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Answer Key

Possible Points: 15 Factor: x1.00 Test Value: 15

Question 10

If then blocks require the VR Robot to make a decision. If the condition is TRUE, then the blocks inside the If then C block are run. If the condition is FALSE, then the blocks inside the If then C block are skipped.



True

1 possible pts.

Question 11

Will this project get the VR Robot through the Disk Maze Challenge successfully?



Answer Key

Possible Points: 15 Factor: x1.00 Test Value: 15

Question 12

Match Conditionals (Block and Switch Block).

C 1.



D 2.



A 3.



B 4.



4 possible pts. / partial credit

